# AMATH 391 Midterm Review

Sibelius Peng Fall 2019

## 1 Week 1

Lec 1 just for information.

#### 1.1 Fourier series

The coefficients of Fourier expansion is given on Midterm Examination FACT SHEET.

The partial sums  $S_N(x)$  are functions that will serve as **approximations** to the function f(x).

$$\lim_{N \to \infty} S_N = f$$

#### 1.2 Metric spaces

A metric space (X, d), is a set X with a "metric" d that assigns nonnegative "distances" between any two elements in X.

- 1. Positivity:  $d(x, y) \ge 0$ , d(x, x) = 0
- 2. Strict positivity:  $d(x, y) = 0 \implies x = y$
- 3. Symmetry: d(x, y) = d(y, x)
- 4.  $\triangle$  inequality:  $d(x, y) \leq d(x, z) + d(z, y)$

#### 1.2.1 Metric spaces for functions

listed in fact sheet.

## 2 Week 2

#### 2.1 Convergence

Cauchy sequence: for any  $\varepsilon > 0$ , there exists  $N_{\varepsilon} > 0$  such that

$$d(x_n, x_m) < \varepsilon \quad \text{for all } n, m > N_{\varepsilon}$$

**Defn** Complete metric space: if all every Cauchy sequence  $\{x_n\}$  converges (to an element  $x \in X$ ) Convergence in  $d_{\infty}$  implies not only pointwise convergence but uniform convergence.

#### 2.2 Normed Linear Spaces

Let X be a vector space. A real-valued function ||x|| defined on X is a norm on X if the following properties are satisfied:

- 1. postivity
- 2. strict positivity  $||x|| = 0 \iff x = 0$
- 3.  $\triangle$  inequality
- 4. homogeneity:  $\|\alpha x\| = |\alpha| \|x\|$

The pair  $(X, \|\cdot\|)$  is called a **normed linear space**. And it is a metric space.

If we consider a normed linear space X as a metric space d, then we may ask whether it is complete.

**Defn** A complete normed space is called **Banach space**.

#### 2.3 Best approximation

Examples:

1. X = C[a, b]. The set of functions  $\{1, x, x^2, \ldots\}$ : linearly independent set.

$$\min_{c_0,\dots,c_{n-1}} \|f - v_n\| = \min_{c_0,\dots,c_{n-1}} \max_{x \in [a,b]} |f(x) - c_0 - c_1 x - \dots - c_{n-1} x^{n-1}|$$

Special case: n = 1.  $d_{\infty}(f, c)$ 

- 2.  $X = L^1[a, b]$ . Special case n = 1.
- 3.  $X = L^2[a, b]$ 
  - (a) n = 1. Two methods:
    - expand the integrand and integrate to produce an expression for  $\Delta_2^2(c)$  in terms of c.
    - use Lebiniz's Rule to differentiate the integral.
  - (b) special case n = 2:  $f(x) \approx c_0 + c_1 x$ . Then minimize

$$h(c_0, c_1) = \Delta_2^2(c_0 c_1)$$

Critical points  $(c_0, c_1)$  must satisfy the following stationarity conditions:

$$\frac{\partial h}{\partial c_0} = \frac{\partial h}{\partial c_1} = 0$$

4. We return to the approx. that yielded by partial sums of the Fourier series of a function f(x) defined on the interval  $[-\pi, \pi]$ . We simply state that  $S_N(x)$  is the best approximation to f(x) in this 2N + 1dimensional space.

#### 2.4 Inner product spaces

The inner product satisfies the following conditions:

1. 
$$\langle x + y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$$

2. 
$$\langle \alpha x, y \rangle = \alpha \langle x, y \rangle$$

- 3.  $\langle x, y \rangle = \langle y, z \rangle$ . If the field of scalars is  $\mathbb{C}$ , then this becomes  $\langle x, y \rangle = \overline{\langle y, x \rangle}$
- 4.  $\langle x, x \rangle \ge 0$

We then say that  $(X, \langle, \rangle)$  is an inner product space.

An inner product defines a norm which, in tun, defines a metric.

A complete inner product space is called a **Hilbert space**.

#### 2.4.1 Orthogonality in inner product spaces

convex, direct sum of two subspaces (algebraic complements). orthogonal complement:  $S, S^{\perp}$ .

#### 2.5 Projection Theorem

Let H be a Hilbert space and  $Y \subset H$  any closed subspace of H. Now let  $Z = Y^{\perp}$ . Then for any  $x \in H$ , there is a unique decomposition of the form

$$x = y + z, \qquad y \in Y, \ z \in Z = Y^{\perp}$$

The point y is called the (orthogonal) projection of x on Y.

mapping  $P_Y: H \to Y$ , the projection of H onto Y. This is idempotent operator:  $P_Y^2 = P_Y$ .

#### 2.5.1 Best approximations in Hilbert spaces

**Theorem** Let  $\{e_1, \ldots, e_n\}$  be an orthonormal set in a Hilbert space H. Define  $Y = \text{span}\{e_i\}_{i=1}^n$ . Y is a subspace of H. Then for any  $x \in H$ , the best approximation of x in Y is given by the unique element

$$y = P_Y(x) = \sum_{k=1}^n c_k e_k$$

where

$$c_k = \langle x, e_k \rangle$$

Furthermore, **Bessel's inequality** 

$$\sum_{k=1}^{n} |c_k|^2 \le ||x||^2$$

## 3 Week 3

## 3.1 Complete orthonormal basis sets - "Generalized Fourier series"

**Defn** An orthonormal set  $\{e_k\}_1^\infty$  is said to be complete or maximal if the following is true: If  $\langle x, e_k \rangle = 0$  for all  $k \ge 1$  then x = 0

Here is the main result:

For any  $x \in H$ , (Generalized Fourier Series)

$$x = \sum_{k=1}^{\infty} \left\langle x, e_k \right\rangle e_k$$

Parseval's equation:

$$||x||^{2} = \sum_{k=1}^{\infty} |\langle x, e_{k} \rangle|^{2}$$

#### 3.2 Convergence of Fourier series expansions

pointwise/uniform convergence, convergence in mean.

uniform  $\implies$  convergence in mean.

#### 3.3 Higher variation means higher frequencies are needed

not be examined.

#### 3.4 even and odd extensions

#### 3.5 Discrete Fourier Transform

In the signal processing literature, the usual notation for such a **sampling** is as follows,

$$f[n] := f(nT), \quad n \in \{0, 1, 2, \ldots\} \text{ or } n \in \{\ldots, -1, 0, 1, \ldots\}$$

## 4 Week 4

## 4.1 An orthonormal periodic basis in $\mathbb{C}^N$

inner product:  $\langle f,g\rangle = \sum_{n=0}^{N-1} f[n]\overline{g[n]}$ 

normalized:

$$u_k = (u_k[0], \dots, u_k[N-1])$$

with components

$$u_k[n] = \frac{1}{\sqrt{N}} \exp\left(\frac{i2\pi kn}{N}\right), \qquad n = 0, 1, \dots, N-1$$

index n plays the role of time or spatial variable and k is the index of the frequency.

#### 4.2 DFT version 3

Given in fact sheet.

#### 4.2.1 Some examples

constant signal: only frequency is zero frequency

linearity of DFT.

real-valued signal can have complex-valued DFT.

$$||f||^2 = \frac{1}{N} ||F||^2$$

Important result: The N-point DFT of the sampled function  $\exp(ik_0x), 0 \le x \le 2\pi$ , is given by a single peak:

$$F[k] = \begin{cases} N, & k = k_0 \mod N\\ 0, & \text{otherwise} \end{cases}$$

#### 4.3 Some properties

We should be able to derive them...

4.3.1 Linearity

$$\mathcal{F}(f+g) = \mathcal{F}f + \mathcal{F}g$$

by defn

#### 4.3.2 Conjugate symmetry

$$F[k] = F[N-k]$$

Note that  $\exp(-i2\pi n) = 1$ 

#### 4.3.3 Shift Theorem

See fact sheet

**Proof** By defn

$$G[k] = \sum_{n=0}^{N-1} g[n] \exp\left(-\frac{i2\pi kn}{N}\right)$$
$$= \sum_{n=0}^{N-1} f[n+1] \exp\left(-\frac{i2\pi kn}{N}\right)$$
$$= \sum_{n=0}^{N-1} f[n+1] \exp\left(-\frac{i2\pi k(n+1)}{N}\right) \exp\left(\frac{i2\pi k}{N}\right)$$
$$= \omega^{-k} F[k]$$

#### 4.3.4 Convolution Theorem

Proof by defn.

$$\begin{aligned} H[k] &= \sum_{n=0}^{N-1} h[n] \exp\left(-\frac{i2\pi kn}{N}\right) \\ &= \sum_{n=0}^{N-1} \left[\sum_{j=0}^{N-1} f[j]g[n-j]\right] \exp\left(-\frac{i2\pi kn}{N}\right) \\ &= \sum_{j=0}^{N-1} f[j] \exp\left(-\frac{i2\pi kj}{N}\right) \sum_{n=0}^{N-1} g[n-j] \exp\left(-\frac{i2\pi k(n-j)}{N}\right) \\ &= \left[\sum_{j=0}^{N-1} f[j] \exp\left(-\frac{i2\pi kj}{N}\right)\right] \left[\sum_{l=0}^{N-1} g[l] \exp\left(-\frac{i2\pi kl}{N}\right)\right] \\ &= F[k]G[k] \end{aligned}$$

The second-to-last line follows the fact from that the products f[j]g[n-j] exhaust all possible pairs since the vectors are N-periodic.

$$|F[N-k]| = |F[k]|$$

## 5 Week 5

By "denosing" the signal f, we mean finding approximations to the noiseless signal  $f_0$ .

#### 5.1 A closer look at Conv. Thm

h = f \* g

In this way, we can view f as a signal, and g as a mask: the conv. the produces a new signal h from f.

#### 5.2 Averaging as a convolution

In the frequency domain, local averaging is shown to perform the greatest shrinkage of DFT coefficients in the high frequency region.

#### 5.3 DCT

eliminate convergence problems due to discont. at the endpoints. True even extension.

## 6 Week 6

### 6.1 DFT of 2-d datasets

tensor product basis. In matlab, they are fft2 and ifft2.

#### 6.2 Fourier Transform

$$f(x) = \sum_{-\infty}^{\infty} a_n e^{in\pi x/L}$$

represents an expansion of the function f(x) in terms of its frequency components.

- The Fourier series is a summation over discrete frequencies  $\omega_n$
- The Fourier transform is an integration over continuous frequencies  $\omega$ .

#### 6.2.1 Import Properties

1. Linearity

2. 
$$\mathcal{F}(t^n f(t)) = i^n F^{(n)}(\omega)$$

3.  $\mathcal{F}^{-1}(\omega^n F(\omega)) = (-i)^n f^{(n)}(t)$ 

4. 
$$\mathcal{F}(f^{(n)}(t)) = (i\omega)^n F(\omega)$$

5. 
$$\mathcal{F}^{-1}(F^{(n)}(\omega)) = (-it)^n f(t)$$

6. 
$$\mathcal{F}(f(t-a)) = e^{-\omega a} F(\omega)$$

7.  $\mathcal{F}(e^{i\omega_0 t} f(t)) = F(\omega - \omega_0)$ 

8. For a 
$$b > 0$$
,  $\mathcal{F}(f(bt)) = \frac{1}{b} F\left(\frac{\omega}{b}\right)$ 

9. Convolution Theorem

#### 6.2.2 Frequency Shift Thm

number 7 of the properties above.

We may be interested in computing the FT of the product of either  $\cos \omega_0 t$  or  $\sin \omega_0 t$  with a function f(t), which are known as **(amplitude) modulations** of f(t).

#### 6.2.3 Scaling Thm

number 8.

Suppose b > 1. g(t) = f(bt) is obtained by contracting the latter horizontally toward y-axis by a factor of  $\frac{1}{b}$ .

G is obtained by stretching F outward.

## 6.3 Plancherel Formula

Using complex inner product:

$$\langle f, g \rangle = \langle F, G \rangle$$

norm-preserving. Can be viewed as the continuous version of Parseval's equation.

## 6.4 The FT of a Gaussian

The sdv of  $f_{\sigma}(t)$  is  $\sigma$ , while  $F_{\sigma}(\omega)$  is  $\sigma^{-1}$ . Consequence of the complementarity of time (or space) and frequency domains.

## 7 Week 7

Lecture 18 only

## 7.1 Convolution thm version 2

$$\mathcal{F}(f \ast g) = \sqrt{2\pi} FG$$

and version 2:

$$\mathcal{F}[f(t)g(t)] = \frac{1}{\sqrt{2\pi}}(F * G)(\omega)$$

# A product of functions in one representation is equivalent to a convolution in the other.

## 7.2 Using Conv. Thm to reduce high freq

#### 7.2.1 low-pass filter

$$H_{\omega_0}(\omega) = F(\omega)B_{\omega_0}(\omega)$$

 $B_{\omega_0}(\omega)$  is a boxcar-type function.

#### 7.2.2 Gaussian weighting

One may wish to employ smoother.

$$G_{\kappa}(\omega) = e^{-\frac{\omega^2}{2\kappa^2}}$$

(we have not normalized in order to ensure  $G_\kappa(0)=1)$ 

Gaussian-weighted FT:

$$H_{\kappa}(\omega) = F(\omega)G_{\kappa}(\omega)$$